

# Towards using probabilistic models to design software systems with inherent uncertainty

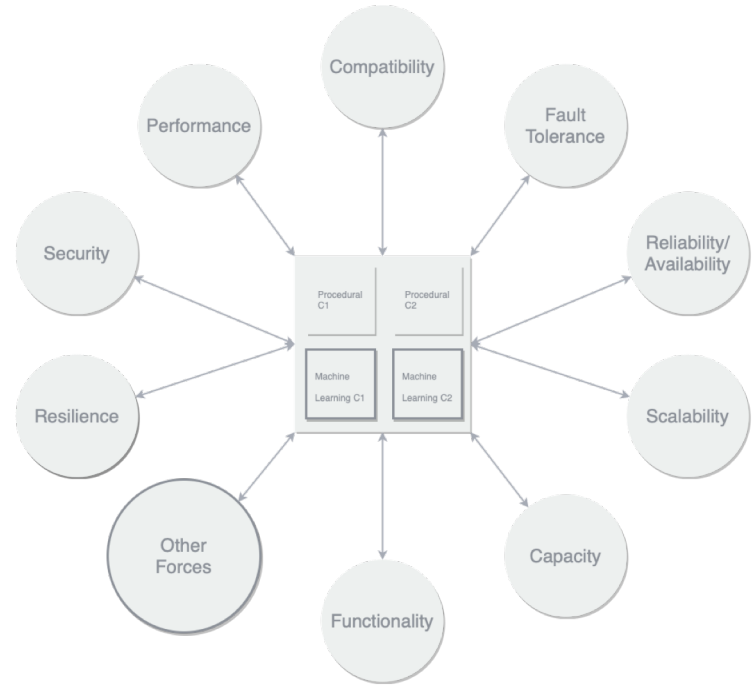
Alex Serban, Erik Poll, Joost Visser



# Architecture design



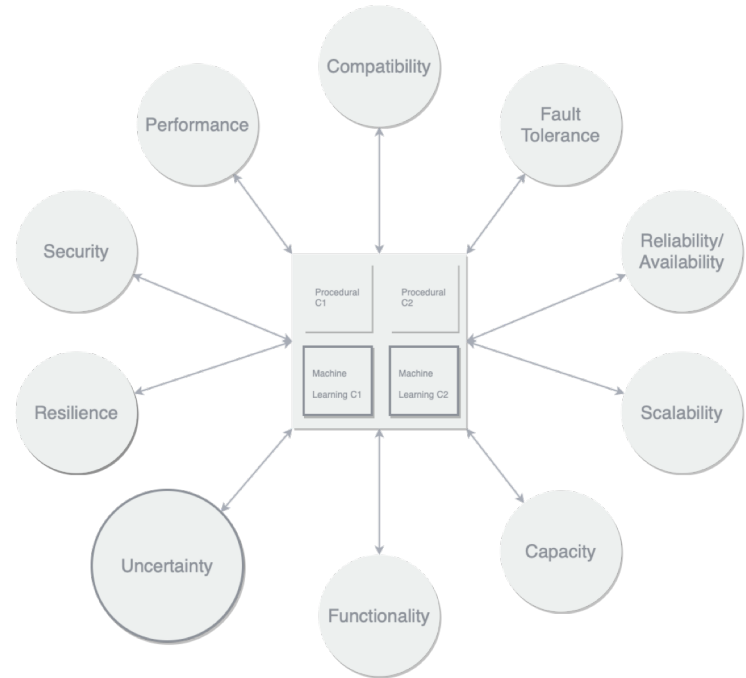
- Software architecture design is a problem that deals with a resolution of forces
- All forces can not be satisfied optimally - in most cases the final solution involves *trade-offs* between different forces
- The question we ask is which are the forces that drive architectural *design* when using machine learning (ML) components?
- The core differences between ML components and other components are: (1) it is not possible to verify that ML components will always *satisfy their intended functionality*, and (2) it is not possible to verify that ML components can *cope with stochastic event during operation*



# Architecture design

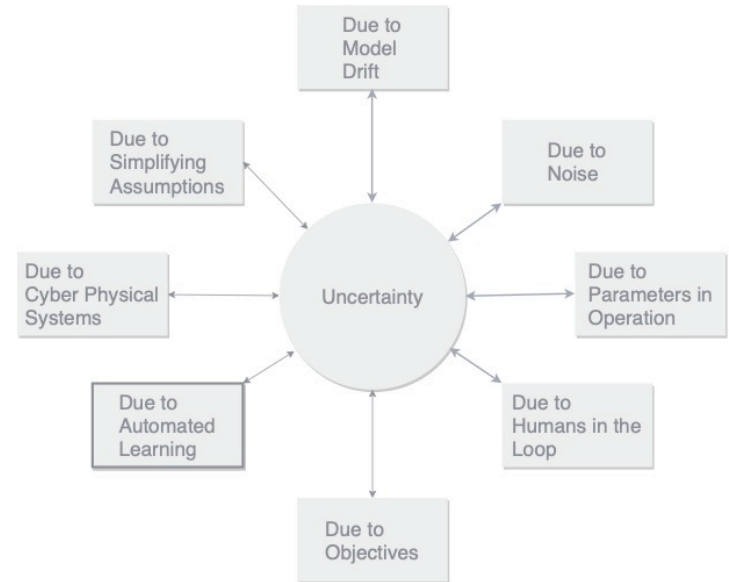


- The question that we ask is which are the forces that drive architectural design when using machine learning (ML) components?
- The core difference between ML components and other component are: (1) it is not possible to verify that ML components will always *satisfy their intended functionality*, and (2) it is not possible to verify that ML components can *cope with stochastic event during operation*
- These differences are due to *inherent uncertainty* in ML components



# Uncertainty in software architecture

- Uncertainty is not a new concept in software architecture
- Many types of uncertainty have been tackled at *design* time, or at *run* time (self-adaptation)
- However, the uncertainty related to *automated learning* has so far been tackled only at run time (and not to a great extent)\*
- In many case decisions have to be made at *design time* (e.g., autonomous vehicles – SOTIF)

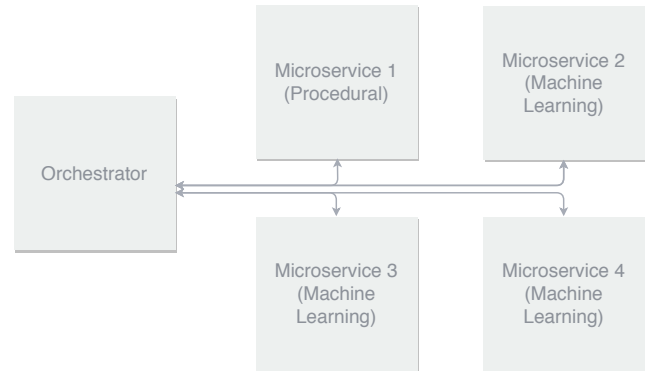


\*Mahdavi-Hezavehi Sara, Avgeriou Paris, Weyns, Danny - A Protocol for a Classification Framework of Uncertainty in Architecture-based Self-Adaptive Systems with Multiple Quality Requirements

Taxonomy by Perez-Palacin, Diego Mirandola, Raffaella,- Uncertainties in the modeling of self-adaptive systems: A taxonomy and an example of availability evaluation

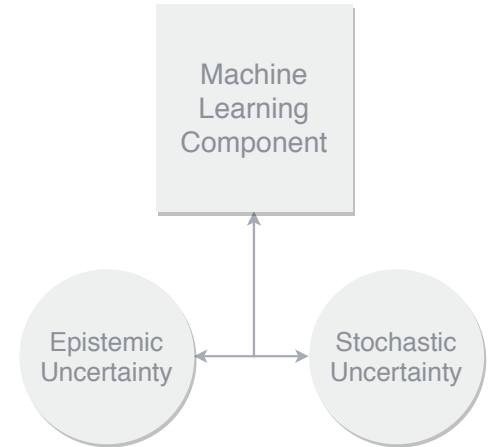
# Modeling uncertainty during design

- We propose to elevate uncertainty due to automated learning at design time, and use it as an architectural decision driver (e.g., as a way to divide / orchestrate microservices)
- And use a modeling approach that can:
  - Take into account the fact that at design time the uncertainty estimates can be subject to change (i.e., the prior information about a component is incomplete)
  - Evaluate uncertainty locally (as it impacts one component) and globally, as it propagates through a system



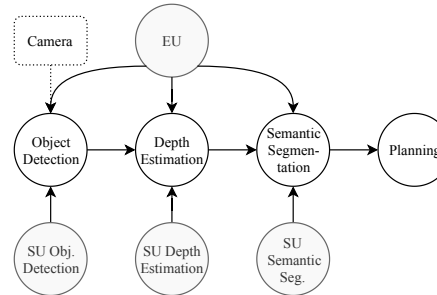
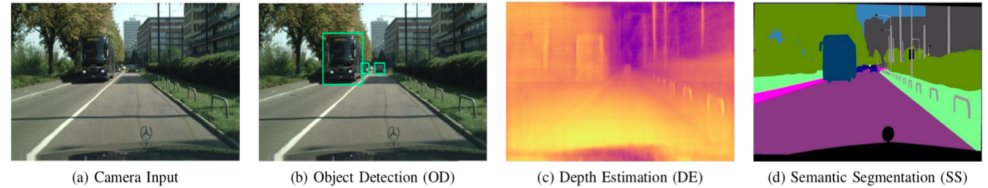
# Types of uncertainty

- All ML algorithms are subject to two types of uncertainty:
  - *Epistemic* uncertainty - captures our ignorance of the correct model that generates the data. This uncertainty can be removed given enough training data
  - *Stochastic* uncertainty - captures the response of a ML component to stochastic events in the operational environment (e.g., noise in the observations).
- We propose to use these 2 types of uncertainty as design elements

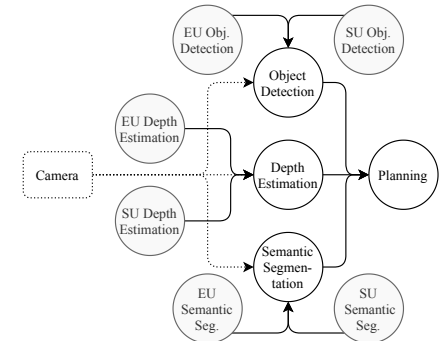


# Use case

- In order to validate if uncertainty can be used at design time, we selected a perception system for autonomous vehicles
- The system performs there tasks which can only be implemented using ML
- For this system we have selected two architectures from literature
- We propose to explicitly model the two types of uncertainty in the architecture (i.e., to annotate the architectures)



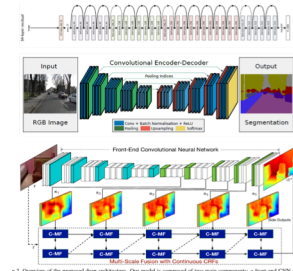
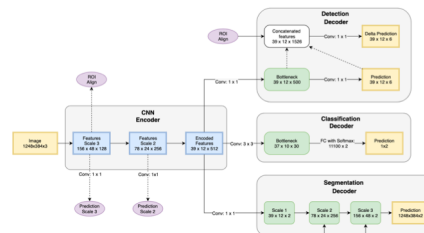
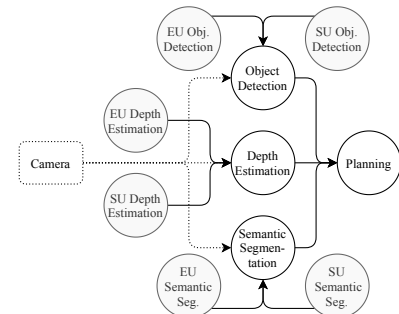
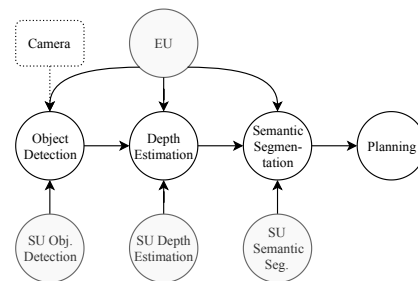
End-to-end architecture



Component-based architecture

# Implementation details

- The end-to-end architecture is implemented with a variant of MultiNet, which shares a base encoder for all tasks and has different individual decoders
  - All components have the same epistemic uncertainty (EU),
  - But different stochastic uncertainties (SU)
- In the component based architecture we train separate models for all tasks
  - All components have different EU and SU
- We extract individual uncertainties and their propagation from the CityScene dataset
- For simplicity, we only represent discrete values for uncertainty (high and low)



$P(\cdot)$	EU	SU	OD	DE	SS
H	0.18	0.16	0.11	0.19	
$P(DE)$	EU	SU	OD	DE	SS
0.0	L	L	L	0.0	L
0.13	L	L	H	0.28	L
0.76	L	H	L	0.64	L
0.85	L	H	H	0.72	L
0.43	H	L	L	0.66	H
0.78	H	L	H	0.58	H
0.9	H	H	L	0.61	H
1	H	H	H	1	H

$P(OD)$	EU	SU
0.64	L	L
0.61	H	L
1	H	H

$P(Planning)$	SS
0.1	L
0.9	H

$P(\cdot)$	EU	OD	DE	SS
H	0.14	0.16	0.31	0.44
$P(OD)$	EU	SU	DE	SS
0.0	L	L	0.0	L
0.57	L	H	0.51	L
0.41	H	L	0.47	H
1.0	H	H	1	H

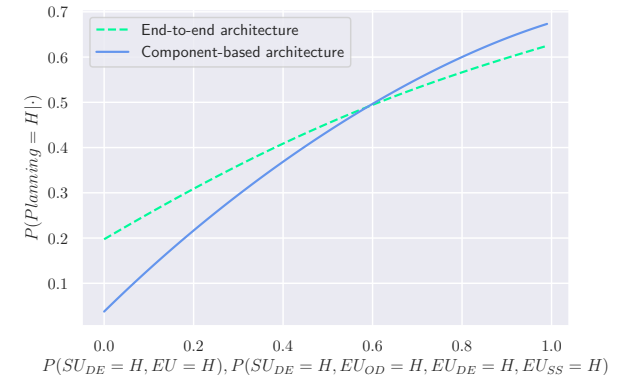
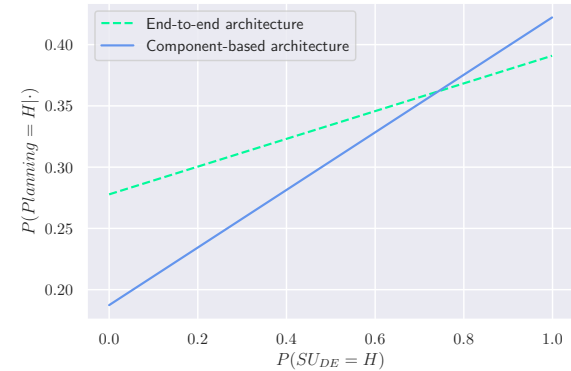
$P(Planning)$	SS	DE	OD
0.0	L	L	L
0.34	L	L	L
0.34	L	H	L
0.11	L	H	H
0.42	H	L	L
1.0	H	H	H



# Evaluation

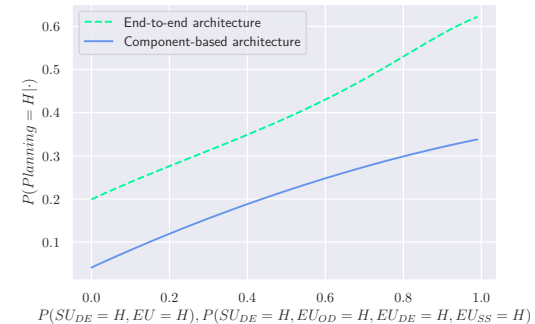
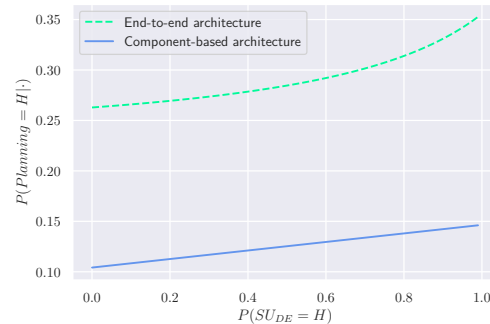
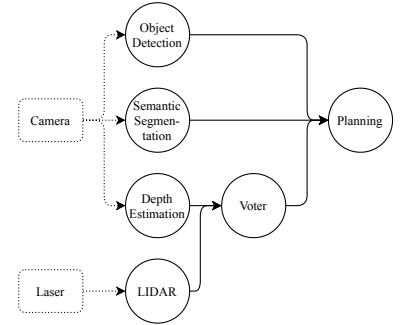
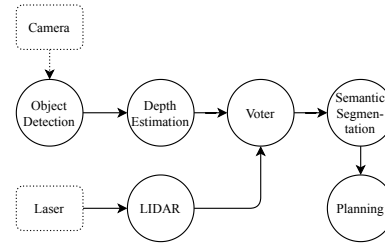


- Under the hood we use Bayesian Networks (BN) to propagate the uncertainties and evaluate trade-offs
- For example, the first plot shows the influence of high stochastic uncertainty for depth estimation in both architectures
- The second plot shows the influence of high stochastic uncertainty for depth estimation and high epistemic uncertainty for all components
- This model allows us to evaluate how any architecture copes with uncertainty, and select the one which is more resilient



# Using patterns to tackle uncertainty

- Using the same methodology we can evaluate architectural changes
- In this case we analyze the use of an n-version programming pattern for depth estimation
- The underlying formalism remains the same, only the uncertainty estimates have to be adjusted
- We observe that the architectures behave differently when this solution is considered



## Conclusions

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Learn more:

<https://tinyurl.com/ml-architect>

- We propose to use the inherent uncertainty of ML components in architecture design
- Elevating uncertainty as a design element can help build robust architectures with ML
- Software architectural patterns can be used to reduce uncertainty
- An interesting avenue for future research is to search for patterns that reduce uncertainty
- A limitation of the current model is the use of Bayesian Networks which allow only directed edges to be modelled (i.e., no cyclical interactions between components)